

What is claimed is:

1. The method for operating a fork-lift truck the lift mast of which that guides a load-carrying means is provided with at least one extraction drive and in which
5 more drives are provided, in case of need, for regulating the lateral position, the inclination and/or the angular position of the load-carrying means relative to the lift mast, wherein the driving speeds of the drives have a maximum upper limit when the load-carrying means is in its highest position, characterized in that the height of the load-carrying means is measured by steps or continuously and the
10 maximum acceleration/deceleration and/or the maximum speed of at least one drive increases with a decreasing height of the load-carrying means.
2. The method for operating a fork-lift truck the lift mast of which that guides a load-carrying means is provided with at least one extraction drive and in which
15 more drives are provided, in case of need, for regulating the lateral position, the inclination and/or the angular position of the load-carrying means relative to the lift mast, wherein the driving speeds of the drives have a maximum upper limit when the load-carrying means is in its highest position, characterized in that the weight of the load is measured on the load-carrying means and the maximum
20 acceleration/deceleration and/or the maximum speed of at least one drive increases with a decreasing weight of the load.
3. The method as claimed in claim 1, characterized in that an interlinking function is formed from the two functions of the maximum acceleration/deceleration
25 and/or that of the maximum speed of at least one drive in dependence of the lift height and the weight of the load, according to which function the acceleration/deceleration and/or speed of at least one drive is set.

4. The method as claimed in claim 2, characterized in that an interlinking function is formed from the two functions of the maximum acceleration/deceleration and/or that of the maximum speed of at least one drive in dependence of the lift height and the weight of the load, according to which function the acceleration/deceleration and/or speed of at least one drive is set.

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